

CORRECTION

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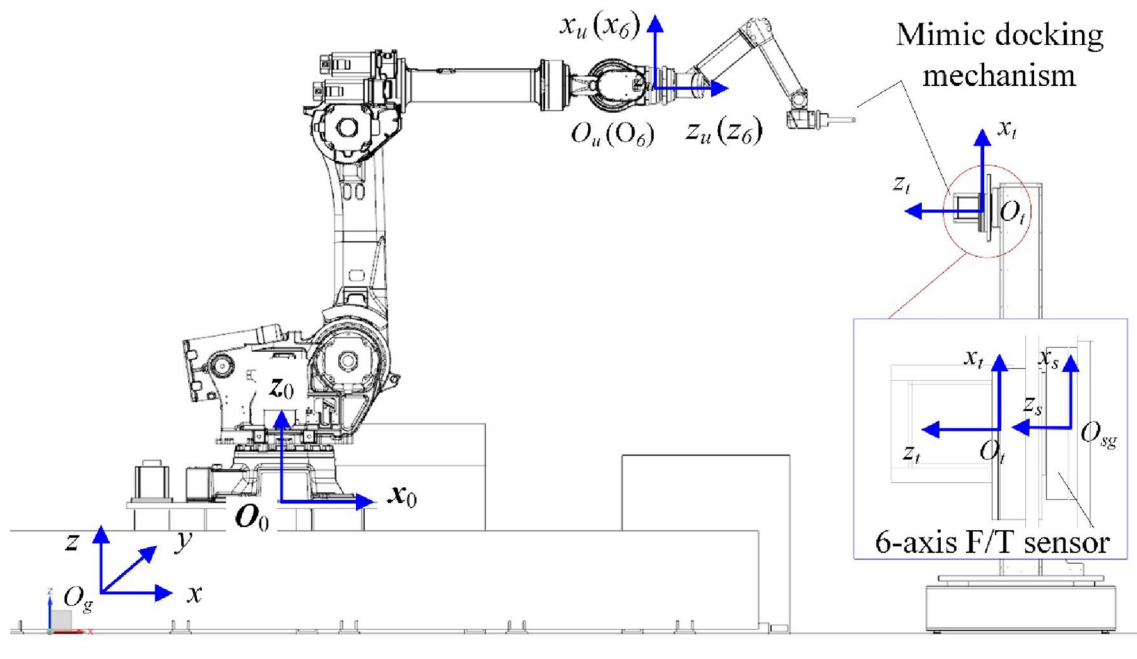


Correction: Active Compliance Control of a Position-Controlled Industrial Robot for Simulating Space Operations

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Correction: Chinese Journal of Mechanical Engineering (2022) 35:149
<https://doi.org/10.1186/s10033-022-00821-1>

In the original publication of this article [1], the figure 2b is incorrect, the correct figure 2b is as below. The original publication has been corrected.



The original article can be found online at <https://doi.org/10.1186/s10033-022-00821-1>.

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