

# Effect of Surface Roughness in Micro-nano Scale on Slotted Waveguide Arrays in Ku-band

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Received: 6 May 2016 / Revised: 7 February 2017 / Accepted: 2 April 2017 / Published online: 12 April 2017  
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**Abstract** Modeling of the roughness in micro-nano scale and its influence have not been fully investigated, however the roughness will cause amplitude and phase errors of the radiating slot, and decrease the precision and efficiency of the SWA in Ku-band. Firstly, the roughness is simulated using the electromechanical coupled(EC) model. The relationship between roughness and the antenna's radiation properties is obtained. For verification, an antenna prototype is manufactured and tested, and the simulation method is introduced. According to the prototype, a contrasting experiment dealing with the flatness of the radiating plane is conducted to test the simulation method. The advantage of the EC model is validated by comparisons of the EC model and two classical roughness models (sine wave and fractal function), which shows that the EC model gives a more accurate description model for roughness, the maximum error is 13%. The existence of roughness strongly broadens the beamwidth and raises the side-lobe level of SWA, which is 1.2 times greater than the ideal antenna. In addition, effect of the EC model's evaluation indices is investigated, the most affected scale of the roughness is found, which is 1/10 of the working wavelength. The proposed research provides the instruction for antenna designing and manufacturing.

**Keywords** Slotted waveguide arrays · Roughness model · Micro/nano-scale · Amplitude and phase errors · Radiation characteristics

## 1 Introduction

A Slotted Waveguide Array(SWA) antenna has the unique advantages of having a compact configuration, stable mechanical characteristics, low loss and high-efficiency, and is consequently widely used in communication systems. However, any structural deficiencies present, such as the surface error on slots and planes [1, 2], have a direct influence on its electrical properties. Although the surface error can be reduced to its limit value by machining the surface as flat as possible, roughness on a micro/nano-scale is inevitable [3–5]. Since a major functionality requirement is that the antenna is expected to operate at high frequencies such as the Ku band, the amplitude of roughness is equivalent to the working wavelength. In this case, roughness will result in amplitude and phase errors of radiating slots, and affect the self-admittance, coupling relationship, and the matching condition of slots, which can adversely affect the antenna's electrical properties [6, 7]. Since this type of antennas is currently developed for high-frequency bands, high gain, low side-lobe level, high performance, ultra-wide band and high precision, the influence of roughness on SWA is becoming a hot topic for research.

Because the electrical performance of a SWA is directly affected by the degradation of its structural characteristics, some researchers have explored different structural factors that influence the antenna's electrical properties. In terms of general array antennas, the prime interest has been on determinations of the pointing gain loss. On this subject, RUZE [8] published the first work related to this field and

Supported by National Natural Science Foundation of China (Grant Nos. 51305322, 51405364, 51475348).

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pursued issues regarding the effect of the position and amplitude-phase errors of radiating elements on the antenna gain loss. HSIAO [9] extrapolated that the effect formula of error on the beam's width, which provided a very beneficial and applicable supplement to extant theories on antenna gain loss. Subsequently, WANG [10] investigated the influence of random errors for each radiating element on the performance of a phased array antenna based on the probability method. However, both RUZE and WANG assumed that the structural error was within a priori determined distribution and failed to analyze practical structural deficiencies through a finite element analysis of the antenna structure. Recently, TAKAHASHI, et al. [11], and SONG, et al. [12], investigated the dynamics related to distortions of the radiating surfaces and their impact on the antenna's electrical performance. However, the majority of research concentrated on the relation between radiating slot information and the electrical performance of the antenna, and an extensive number of research papers has been published on this topic. Research has also been conducted on the relationship between radiating slot information and cavity errors, but no concrete associations have yet been determined. Moreover, the roughness of the inner wall of the radiating waveguide has hardly been studied.

Through his modeling research on the roughness of the waveguide, MORGAN [13] obtained a result which is now considered classical. The following analyses are found to be consistent with MORGAN's results [14–16]. However, in MORGAN's and the other analyses, some periodic functions were used. In the other hand, TSANG, et al. [17], used a random function to simulate roughness, which was characterized using the root mean square (RMS), correlation length, and the correlation function. Certainly, an advantage of using a random model was that it allows a similar approach as in the case of roughness occurring in copper interconnects. LUKIC and FILIPOVIC [18] modeled a rectangular-coaxial roughness by investigating the cubical, semi-ellipsoidal and pyramidal indentation, and his results showed that roughness accounted for up to 9.2% of their overall loss for frequencies below 40 GHz. Nonetheless, the roughness on the radiating waveguide is neither totally random nor clearly deterministic, and the altitude distribution, the slope and curve of the random model are associated with resolution and sampling length of the measuring instrument, while it is not unique [19–21]. Fractal geometry has provided an additional means of description and roughness analysis [22–24]. In our previous works, a one-dimensional fractal analysis of roughness is investigated [25], but the scope of its applicability is limited, because it is based on a deterministic mathematical form.

Based on previous studies, this paper seeks to investigate the relationship between surface roughness and

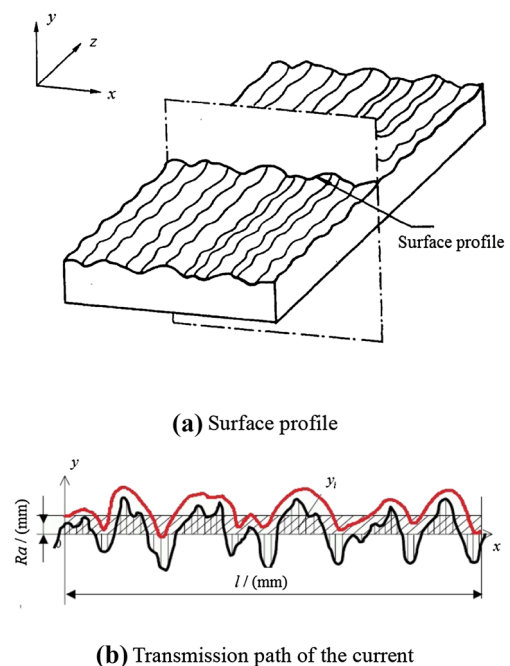
antenna electrical properties. For this reason, an EC model was used to simulate roughness, based on which an influence mechanism equation was deduced.

## 2 Roughness Model

### 2.1 Electromechanical Coupled Roughness Model

In the mechanical field, roughness is the surface profile of an object separated from its surrounding environment, which is the intersection transversal between the vertical plane and actual surface, as shown in Fig. 1(a). However, on the inner wall of a waveguide, the transmission path of the electromagnetic wave is not completely consistent with the surface profile. Even though roughness (black line in Fig. 1(b)), may be bigger or smaller relative to the working wavelength of the waveguide, the surface profile has little influence on the transmission path (red line in Fig. 1(b)) [26]. Therefore, an effective model should be built according to the most influential surface profile, and profile elements that are too big or too small should be considered as sources producing noise and this noise should be filtered out. Since roughness is a basic mechanical parameter, while filtering concerns is the electrical properties, the proposed novel roughness modeling method can be called the electromechanical coupled roughness model and abbreviated as the EC model.

In order to model roughness, a Monte Carlo simulation was first used [27]. Since two dimensional roughness



**Fig. 1** Schematic diagram of the effective roughness model

exhibits waviness in both directions, if we denote the root mean square (RMS) value of roughness as  $Ra$ , then the power spectral density function of the fractal function is [28]

$$S(w_x, w_y) = \left[ G^{2(D-1)} / (2 \ln(\gamma_x \gamma_y) \cdot (w_x w_y)^{(5-2D)}) \right], \quad (1)$$

where  $D$  is the fractal dimension, and  $G$  is the characteristic length,  $\gamma_x = 1/L_x, \gamma_y = 1/L_y$ , where  $L_x$  and  $L_y$  are the sampling lengths of roughness in the  $x$  and  $y$  directions, while  $w_x$  and  $w_y$  are the frequencies of the roughness in the  $x$  and  $y$  directions, respectively. If the power spectral density functions in each direction are  $S(w_x)$  and  $S(w_y)$ , respectively, and  $Ra \propto G^{D-1}$ , then Eq. (1) can be expressed as

$$S(w_x, w_y) = \frac{1}{Ra^2} S(w_x) S(w_y). \quad (2)$$

We performed a uniform discretization of roughness, where the numbers of discrete points in each direction are  $M$  and  $N$ , the corresponding separation distances of adjacent points are  $\Delta x$  and  $\Delta y$ , where  $\Delta x = L_x/M$ ,  $\Delta y = L_y/N$ , and the height of each data points on the surface is given by

$$f(x_m, y_n) = \frac{1}{L_x L_y} \sum_{(m_k=1-M/2)}^{M/2} \sum_{(n_k=1-N/2)}^{N/2} F(k_{mk}, k_{nk}) \exp(i(k_{mk}x_m + k_{nk}y_n)), \quad (3)$$

where  $x_m = m\Delta x, y_n = n\Delta y, m = 1 - M/2 \sim M/2, n = 1 - N/2 \sim N/2$ , while  $F(k_{mk}, k_{nk})$  is given by

$$F(k_{mk}, k_{nk}) = 2\pi \sqrt{L_x L_y S(k_{mk}, k_{nk})}, \quad (4)$$

where  $k_{mk} = 2\pi m_k/L_x$  and  $k_{nk} = 2\pi n_k/L_y$ .

For  $f(x_m, y_n)$  to be real,  $F(k_{mk}, k_{nk})$  should satisfy the relationship:

$$F(k_{mk}, k_{nk}) = F^*(-k_{mk}, -k_{nk}), \quad F(-k_{mk}, k_{nk}) = F^*(k_{mk}, -k_{nk}),$$

where  $F^*(\cdot)$  is the Fourier transformation. Therefore, the roughness model  $f(x, y)$  can be expressed as

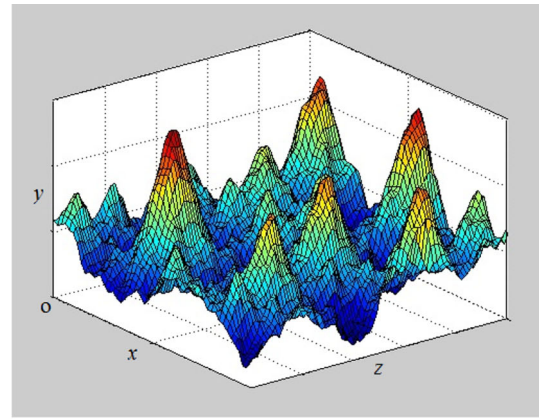
$$f(x, y) = \frac{1}{Ra^2} f(x) f(y), \quad (5)$$

and the one dimension roughness model are

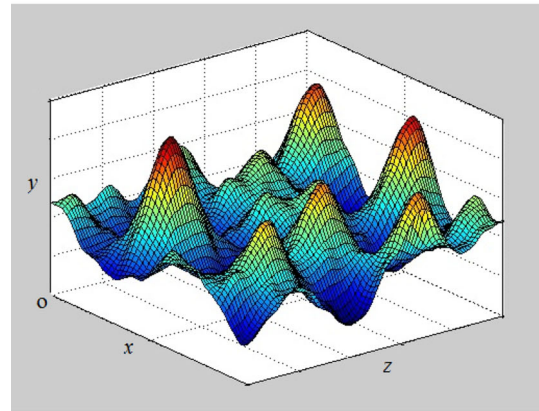
$$f(x) = G^{D-1} \sum_{n=1}^{\infty} \frac{\cos(2\pi\gamma^n x + \varphi_n)}{\gamma^{(2-D)n}}, \quad (6)$$

$$f(y) = G^{D-1} \sum_{m=1}^{\infty} \frac{\cos(2\pi\gamma^m y + \varphi_m)}{\gamma^{(2-D)m}}. \quad (7)$$

As shown in Fig. 2(a), a two-dimensional Weierstrass-Mandelbrot (W-M) fractal function was used as the basic model to describe the surface profile as comprehensively as



(a) Fractal roughness function



(b) Electromechanical coupled function

Fig. 2 Two dimensional roughness model

possible [21]. Then, the effective roughness profile was determined based on the transmission path, and the filter function's upper and lower limits were chosen. Finally, the EC model was built as shown in Fig. 2(b). The specific modeling parameters were detailed and illustrated in subsequent equations. A two-dimensional Gaussian was used as the filter function:

$$h(x, y) = \frac{1}{A^2 \lambda_x \lambda_y} \exp \left[ -\pi(x/A\lambda_{cx})^2 - \pi(y/A\lambda_{cy})^2 \right], \quad (8)$$

where  $\lambda_x$  and  $\lambda_y$  are the working wavelengths in the  $x$  and  $y$  directions, while  $\lambda_{cx}$ ,  $\lambda_{cy}$  and  $A$  are the truncation wavelengths and width coefficient of the filter, respectively.

According to the electrical characteristics of the antenna, 94% of the surface current was distributed within 3 times the skin depth, so the upper and lower limits of the filter are

$$\lambda_{\max} = 2\sqrt{1/(\pi f \mu_0 \sigma)}, \quad (9)$$

$$\lambda_{\min} = \lambda_{\max}/3, \quad (10)$$

the  $f$  is the current frequency of the waveguide, and  $\mu_0$  and  $\sigma$  are the permeability and conductivity of the waveguide's inner wall, respectively.

The basic model given in Eq. (5) can be divided into two parts as

$$f(x, y) = f_1(x, y) + f_2(x, y), \quad (11)$$

where  $f(x, y)$  is the basic model, which is composed of two parts:  $f_1(x, y)$  is the representation of noise in the surface profile, which has little influence on the transmission path of electromagnetic wave, and  $f_2(x, y)$  is the effective profile data, which is just the EC roughness model. Using  $f_1(x, y)$  as the assessment base level:

$$\begin{aligned} f_1(x, y) &= f(x, y) \cdot h(x, y) \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(\xi, \eta) h(x - \xi, y - \eta) d\xi d\eta. \end{aligned} \quad (12)$$

The EC model becomes:

$$\begin{aligned} f_2(x, y) &= f(x, y) - f_1(x, y) \\ &= f(x, y) - \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(\xi, \eta) h(x - \xi, y - \eta) d\xi d\eta. \end{aligned} \quad (13)$$

If the measured data are discrete, the assessment base level  $f_{ij}^1$  becomes

$$f_{ij}^1 = \sum_{k=-M}^M \sum_{l=-N}^N z_{i-k, j-l} h_{k,l} \Delta x \Delta y, \quad (14)$$

where  $i = M, \dots, LX - M$ ;  $j = N, \dots, LY - N$ ,  $h_{k,l} = \frac{1}{\alpha^2 \lambda_{cx} \lambda_{cy}} \exp \left[ -\pi (k \Delta x / \alpha \lambda_{cx})^2 - \pi (l \Delta y / \alpha \lambda_{cy})^2 \right]$ .

The EC model  $f_{ij}^2$  is

$$f_{ij}^2 = f_{ij} - f_{ij}^1 = f_{ij} - \sum_{k=-M}^M \sum_{l=-N}^N f_{i-k, j-l} h_{k,l} \Delta x \Delta y. \quad (15)$$

## 2.2 Evaluation indices of the EC roughness model

Traditional definitions of the surface roughness usually contain only local and one-dimensional information, and the arithmetical mean error  $Ra$  is regarded as the unique evaluation indices [29]. The features of two or three dimensional roughness cannot be fully represented by this conventional index. Moreover,  $Ra$  is a non-deterministic index, which means that different roughness contours processed by different technologies may yield the same  $Ra$ . For the fractal geometric model, two parameters ( $D$  and  $G$ ) are introduced to describe roughness characteristics. Index  $D$  is the dimension parameter, while  $G$  is the fundamental frequency in space and represents roughness density. Although these two indexes allow more accurate roughness

quantification, they cannot be adequately measured directly and it is hard to relate them to the measured parameters of roughness. For these reasons, the applicability of the fractal model is limited. Studies have shown that the main differences between roughness contours processed by different technologies but with the same  $Ra$  are the density and regularity of peaks and valleys. The information appears as the expansion length of the roughness profile, which is the principal reason for changing of the transmission path. Therefore, two parameters,  $Ra$  and  $Rl$  are introduced as the roughness model indexes.  $Ra$  is the main parameter, and its value is equal to the arithmetical mean deviation;  $Rl$  is the auxiliary parameter, and its value is the length of effective roughness contour. The equations for these two indices are

$$\begin{cases} Ra(1) = \frac{1}{l_x} \int_0^{l_x} |f(x)| dx \approx \frac{1}{n} \sum_{i=1}^n |y_i|, \\ Rl(1) = \frac{1}{l_x} \int_0^{l_x} \sqrt{1 + f'^2(x)} dx \approx \frac{1}{l_x} \sum_{i=1}^{n-1} \sqrt{(x_{i+1} - x_i)^2 + (y_{i+1} - y_i)^2}, \end{cases} \quad (16)$$

where  $l_x$  and  $f(x)$  are the sampling length and roughness model in the  $x$  direction, while the  $(x_i, y_i)$  is a discrete measured datum of roughness.

Using the two-dimensional roughness indices as the description model can not only reflect the relief intensity but also the fluctuation gradient for roughness, which required for both mechanical and electromagnetic field analyses. Even though using a calculation based on a one-dimensional model displays a clear mathematical principle and its simple structural equation is easily calculated, it is revealed to be inadequate since the electromagnetic field dispersed over the waveguide inevitably demonstrates some directional properties. Furthermore, the real surface roughness is anisotropic and should be considered simultaneously from the length wise and transverse directions. Thus,  $[Ra(2), Rl(2)]$  for the two-dimensional EC model are formulated as follows:

$$\begin{cases} Ra(2) = \frac{1}{l_x l_y} \int_0^{l_x} \int_0^{l_y} |f(x, y)| dx dy, \\ Rl(2) = \frac{1}{l_x l_y} \int_0^{l_x} \int_0^{l_y} \sqrt{1 + \left( \frac{\partial f}{\partial x} \right)^2 + \left( \frac{\partial f}{\partial y} \right)^2} dx dy. \end{cases} \quad (17)$$

## 3 Factors Affecting Roughness

In the field of antenna error analysis, there existed a number of papers dealing with the effect of imperfections in the waveguide cavity on radiating the slots' error. For an

antenna working in the GHz range, roughness of the waveguide becomes a critical reason for position and directional offset of the radiation slot. Therefore, in order to establish a connection between the roughness and radiating slot error, the key difficulty lies in antenna error analysis. Based on the model  $f(x, y)$ , the roughness information should be primarily represented using antenna coordinates [30].

Given a point on the roughness surface  $A(x_A, y_A, z_A)$  and an angle  $\alpha$ , an elliptical curve can be obtained using a line drawn through the point  $A$ , whose axis is the origin and  $\alpha$  is the angle. Let the center of this ellipse be  $Q(x_Q, y_Q, z_Q)$  and an intersection point of the axis and the ellipse be denoted by  $S(x_S, y_S, z_S)$ . Thus, an area corresponding to the roughness coordinate  $\delta(x_n^\delta, y_n^\delta, z_n^\delta)$  is established, where the point  $Q$  is its origin and the elliptical surface is on the  $x_n^\delta o y_n^\delta$  plane. If the antenna coordinate is  $(x, y, z)$ , the transformation process needs to be shifted twice and rotated as follows:

$$\begin{pmatrix} x_0 \\ y_0 \\ z_0 + z_Q \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \omega_x & -\sin \omega_x \\ 0 & \sin \omega_x & \cos \omega_x \end{pmatrix} \begin{pmatrix} x_n^\delta \\ y_n^\delta \\ z_n^\delta \end{pmatrix}, \quad (18)$$

$$\begin{pmatrix} x + x_Q \\ y + y_Q \\ z \end{pmatrix} = \begin{pmatrix} \cos \omega_z & \sin \omega_z & 0 \\ -\sin \omega_z & \cos \omega_z & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_0 \\ y_0 \\ z_0 \end{pmatrix}, \quad (19)$$

where  $\omega_x = \pi/2 - \omega'_x$ , and  $\omega'_x$  can be deduced by  $\tan \omega'_x = \frac{\cos \beta + \cos \alpha}{\sin \beta}$ , while  $(x_0, y_0, z_0)$  is the intermediate coordinate during the transformation process.

If the roughness model is  $z_n^\delta(x_n^\delta, y_n^\delta)$ , then according to Eqs. (18), (19), the slot error characteristics are

$$\Delta \vec{r}_n = \left| \sqrt{x^2 + y^2 + z^2} - \sqrt{x_n^{2\delta} + y_n^{2\delta} + z_n^{2\delta}} \right|, \quad (20)$$

$$\zeta_{\theta n} = \left| \arccos(z/x) - \arccos(z_n^\delta/x_n^\delta) \right|, \quad (21)$$

$$\zeta_{\varphi n} = \left| \arctan(y/x) - \arctan(y_n^\delta/x_n^\delta) \right|. \quad (22)$$

If the excitation current of unit  $n$  is  $I_n$ , its coordinate are  $(x_n, y_n, z_n)$ , and  $I_n$  is symmetrical on two coordinate axes, the radiation field intensity of the antenna on the plane ( $\varphi = \varphi_0$ ) is [31]

$$E_0(\theta, \varphi_0) = \sum_n I_n \exp j[k(x_n d_x \cos \varphi_0 + y_n d_y \sin \varphi_0) \cdot (\sin \theta - \sin \theta_0)] / \sum_n I_n, \quad (23)$$

where  $E_0(\theta, \varphi_0)$  is the far field pattern,  $\theta, \varphi$  are the azimuth in the far field,  $d_x$  and  $d_y$  are the distances of the array element,  $x_n$  and  $y_n$  are the position coordinates of unit  $n$ , and  $k$  is the transfer constant. When the position error of

unit  $n$  is  $(x_n^\delta, y_n^\delta, z_n^\delta)$ , the radiation field intensity becomes as follows:

$$E_0(\theta, \varphi) = \sum_n J_n \exp j[k((x_n + x_n^\delta) d_x \cos \varphi_0 + (y_n + y_n^\delta) d_y \sin \varphi_0)(\sin \theta - \sin \theta_0)] / \sum_n J_n, \quad (24)$$

where

$$J_n = I_n \exp j[k(x_n^\delta d_x \cos(\varphi + \zeta_{\varphi n}) + y_n^\delta d_y \sin(\varphi + \zeta_{\varphi n})) \sin(\theta + \zeta_{\theta n}) + k z_n^\delta d_z \cos(\theta + \zeta_{\theta n})].$$

## 4 Testing of Proposed Methods

### 4.1 Experiment on a planar slot antenna

In order to provide evidence supporting the EC roughness model and how factors related to its influence antenna performance, a miniature planar slot array antenna was processed as an experimental project case. The antenna operated in the Ku band, with a central frequency of 12 GHz, a gain of no less than 17 dB, and the first lobe level was no higher than -16 dB. Its structural dimensions were 150 mm  $\times$  126 mm, and it had ten radiating waveguides and eight vertical offset slots on each waveguide.

Roughness on the inner wall of the radiating waveguides was measured using the Taylor Hobson profile measuring instrument. Indexes  $Ra$  and  $Rl$  of the measurement data [ $Ra^1, Rl^1$ ] and the EC roughness model [ $Ra^2, Rl^2$ ] were calculated as follows:

$$Ra^1 = \frac{1}{l_x} \int_0^{l_x} |z(x)| dx, \quad (25)$$

$$Ra^2 < \frac{2G^{D-1}}{\pi} \cdot \frac{\gamma^{(D-2)n}}{1 - \gamma^{D-2}}, \quad Ra^2 \propto G^{D-1}, \quad (26)$$

$$Rl^1 = \sqrt{\frac{1}{m} \sum_{i=1}^m f(x_i)^2}, \quad (27)$$

$$Rl^2 = \int_{w_1}^{w_2} S(w) dw = \frac{G^{(D-1)}}{w^{(2-D)} [2 \ln \gamma^{(4-2D)}]^{1/2}}. \quad (28)$$

In the equations,  $w_2$  is the measuring resolution,  $w_1$  is the sampling length,  $D$  is the fractal dimension, and  $G$  is the characteristic length. To validate the EC model, three regions (S1, S2 and S3) on the radiating surface were chosen, and the indexes of the measurement data and the EC model on these regions were shown in Table 1. The RMS value for S1 is 0.495 mm, for S2 it is 1.477 mm and



**Table 1** Comparison of two indexes of measurement data and EC model

Methods	Indexes	Region S <sub>1</sub>	Region S <sub>2</sub>	Region S <sub>3</sub>
Measurement	Ra/mm	0.495	1.477	0.703
	Rl/mm	0.874	3.453	1.367
EC model	Ra/mm	0.508	1.501	0.635
	Rl/mm	0.970	3.415	1.248

for S3 it is 0.703 mm, with a maximum error of 13%, which demonstrates the accuracy of the EC model.

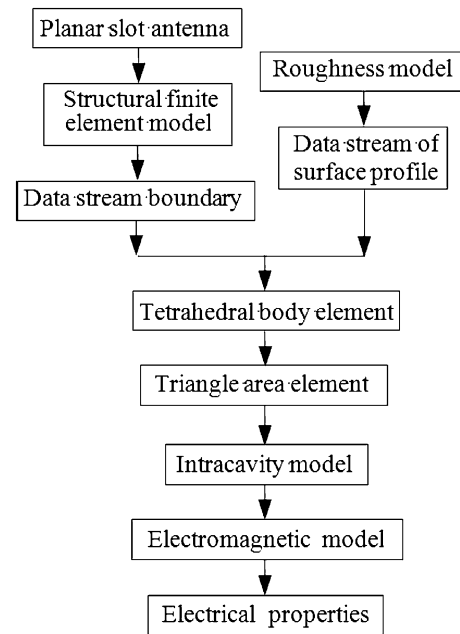
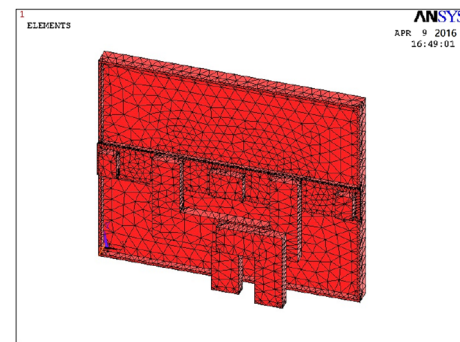
The antenna was fixed on the test turning platform to ensure that the radiating plane was parallel to the direction of gravity and the scanning plane of the measuring waveguide probe. The near-field data of the antenna was measured by the plane near-field scanning method, while the far-field data were obtained through the near-field to far-field transformation (nffft) method [32, 33]. The plotting radiating pattern is for the H-plane. The electrical performance was evaluated using the antenna gain, the maximum sidelobe level, and the 3-dB beamwidth on azimuth plane, as well as the maximum sidelobe level, and 3-dB beamwidth on the pitch plane.

#### 4.2 Simulation of the SWA with Roughness

High-precision characteristics of SWA result in high costs and a long manufacturing cycle. Thus, manufacturing antennas in large quantities for experimental reasons is difficult and even impractical. Therefore, antenna simulation analysis is gaining increasing attention and interest from the scientific and industrial community, because of repeatability and low cost. However, the key to accurate simulations is to incorporate surface roughness in the numerical model. Only a small number of existing commercial software can accurately analyze the antenna taking roughness into account, and the structural and electromagnetic analyses are usually carried out separately, which will cause a mismatch in structural and electromagnetic meshes. In order to deal with these issues, the grid conversion and roughness data adding methods are presented in this paper. As shown in Fig. 3, the simulation was conducted as follows:

First, the finite element model of the antenna was constructed using ANSYS 11.0, as shown in Fig. 4. The number of nodes was 19263, while there were 55169 units. The material chosen was Al-6063, with a modulus of elasticity of 70 GPa, a Poisson ratio of 0.33, and a density of  $2.7 \times 10^3$  (kg·m<sup>-3</sup>).

The second step was to add the roughness information to the ideal antenna model. The structural boundary of the antenna was determined by the shape of the data stream, and the roughness model was added into it as an additional

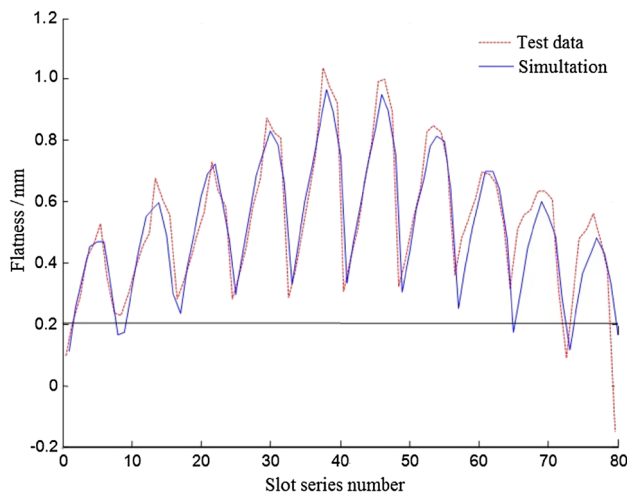
**Fig. 3** Simulation process of the antenna with roughness**Fig. 4** Finite element model of the antenna array

boundary. The finite element model of the antenna with roughness was built using the GUI.

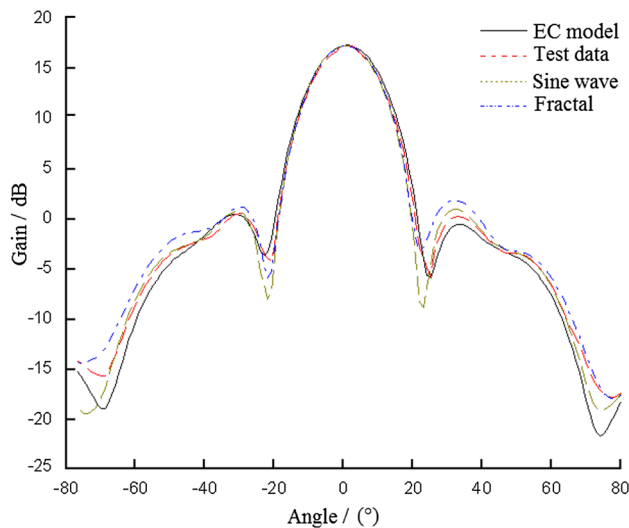
The third step was to translate the structural model to an electromagnetic analysis model by converting the tetrahedral body elements of the structural model into triangular surface elements, which were necessary for the electromagnetic analysis. Based on the surface elements, a surface model of the antenna was built and the intracavity model was extracted from it. Finally, the intracavity model of the antenna was introduced into HFSS 11.0 and the electrical properties of the model were obtained.

#### 4.3 Results and Discussion

To verify the accuracy of the proposed simulation method, a flatness comparison of the radiating plane was made between the simulation results and the test data, as shown in Fig. 5, where the series of radiating slots forms the



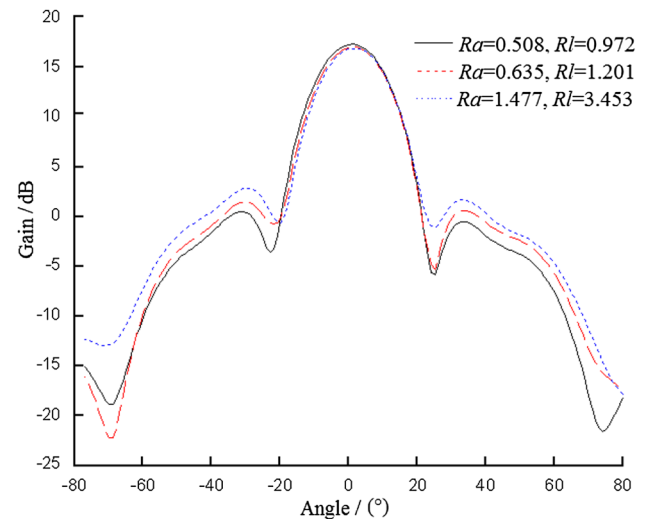
**Fig. 5** Flatness comparison of the simulation result to the test data



**Fig. 6** Comparison of different models to the test data of the antenna pattern

abscissa and the  $z$  component was the vertical coordinate. The simulation results along with the slot numbers are all highly consistent with the test data results. A small error occurs, because the simulation was based on an antenna working under ideal circumstances, which was not the case in the practical antenna test.

To verify the proposed roughness model, a comparison was made using the test data of the antenna pattern, where the sine wave represents the period model and the Gaussian represents the random model. As shown in Fig. 6, the results of the periodic model (based on the sine wave approximation) have a lower first side-lobe than the test data, because most of the roughness information has been lost. The results obtained from the performance degradation analysis of the fractal model appears more severe than



**Fig. 7** Comparison of different roughness indexes of the antenna pattern

the result of the periodic models, due to the fact that the fractal model contains more roughness information, which severely changes the transmission path of the electromagnetic wave. However, it does not completely coincide with the test data, because it is built according to the actual surface profile, not the transmission path. The results of the EC model are closest to the test data, indicating that it can describe the roughness information more precisely than any of the other models can.

As shown in Fig. 7, increasing the roughness indices also broadens the beam width and raises the side-lobe level of the antenna, while it had little impact on the antenna's gain. The antenna is affected the most when the amplitude of roughness is equal to approximately one tenth of the working wavelength. Relative to  $Ra$ ,  $Rl$  has a stronger influence on the first side-lobe level of the antenna. These findings suggest that the strongest influence indexes, and reducing them in the manufacturing process is an effective way to ensure the design accuracy of the antenna, which will greatly reduce the production cost and shorten the production cycle as well.

## 5 Conclusions

- (1) An EC roughness model is presented to characterize the roughness by using the Gaussian filter. Two evaluation indices of the EC model are introduced.
- (2) A Relationship between the roughness and the array's radiation properties is obtained by analyzing the positional difference of the radiating slots.
- (3) A novel simulation method for the non-ideal antenna is introduced.

- (4) Existence of roughness strongly broadens the beam width and raises the side-lobe level of SWA, with the maximum value being 1.2 times greater than obtained by a smooth antenna.
- (5) The most affected scale of the roughness is found, which is 1/10 of the working wavelength.

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